

# Dr. Mohammad Alfraheed

Tafila Technical University

Faculty of Communication and Information  
Technology

Department of Computer Science

# General Information

**2012**

In 2012, I had a Ph.D degree from RWTH-Aachen University which is the one of the best universities in Germany and Europe

**2014**

In 2014, I have been selected for the Endeavour Fellowship to do a post-doctorate in university of technology Sydney in Australia for six months. My research was fully funded by the Endeavour Scholarship

**2012**

In 2012, I hired as assistant professor in Tafila Technical Univerity.

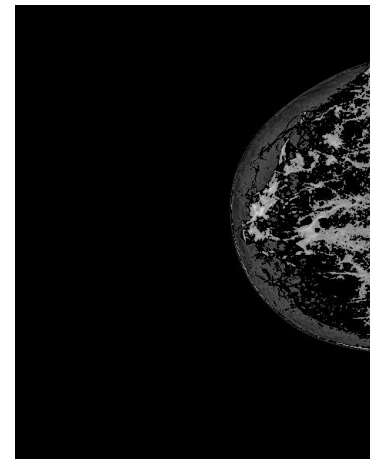
**2015**

In 2015, I hired as a head of the department of computer science at tafila technical university

# General Information

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In 2015, my projects called CCC cancer cell classification has been selected to be funded by Project VI-SEEM which is run in Jordan by SESAME



# General Information

In 2019, the president of Tafila Technical University hired me beside of as an associated professor to manage the consultations, studies and training center

In 2023, I have been selected for FULBRIGHT SCHOLARSHIP to do again a POST-Doctorate research in University of Michigan-dearborn



# Background Research



My interested research filed is in general in computer science. In more details, I prefer to do research in artificial intelligence and computer vision and image processing



I'd to developed news applications not only in medical applications but also in cyber physical system which is mainly coordinate by computer vision



## Future Work

- Two-View Mammogram Synthesis
- Cyber Physical System



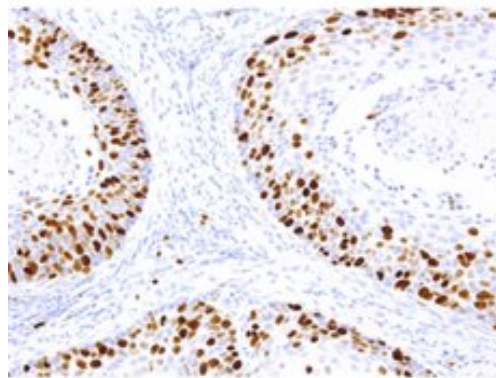
*Amro Aljadaa*

CONTROL SOFTWARE  
ENGINEER @SESAME



## *Background*

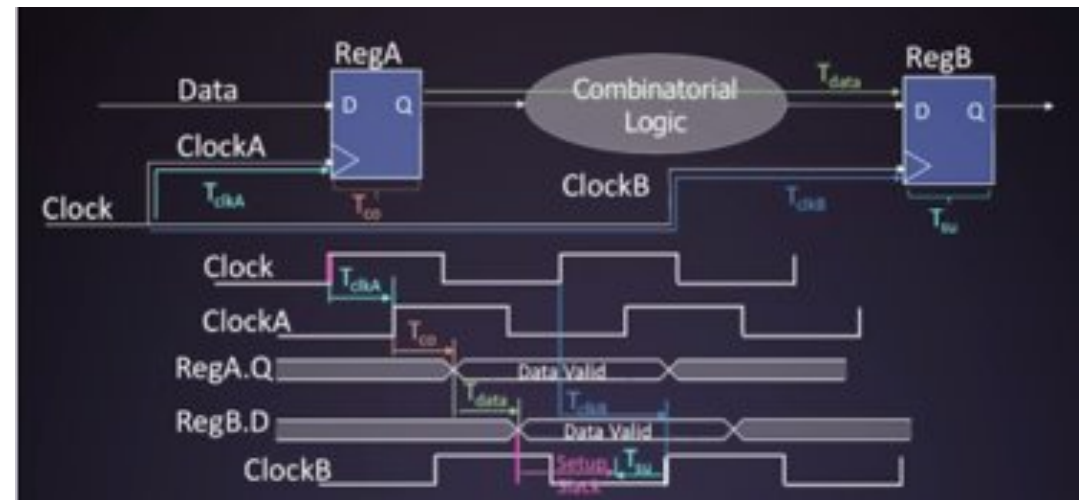
- Electrical Engineering
- Embedded Systems
- Image Processing & AI





# *Background*

- Electronic design automation
- Robotics



# *SESAME*

We use **C++** to:

- Develop graphical user interfaces using Qt
- Develop Drivers for controllers



# *SESAME*

We use **Python** to write scripts that perform various services for the machine, including:

- monitoring machine performance
- Controlling motors
- Image Processing
- Event driven systems



# *ARM Robot*

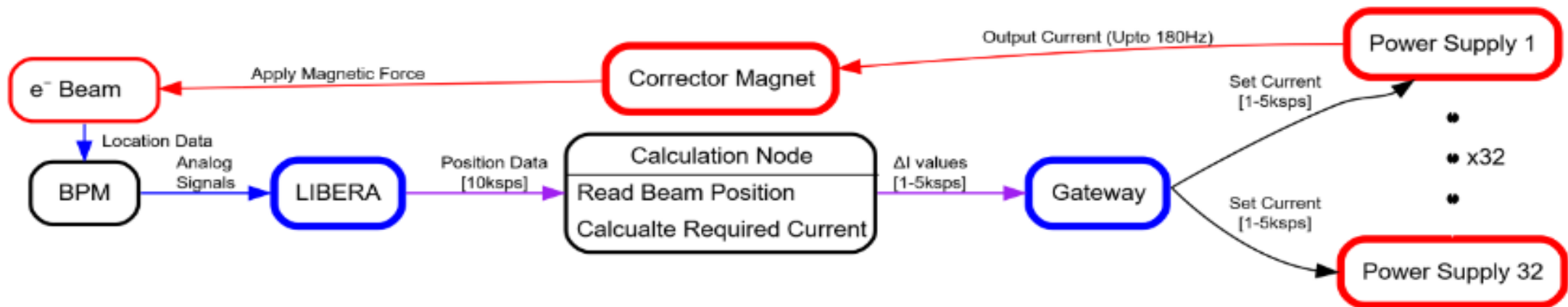
- Sample changing in MS beamline
- State driven control
- Safety features
- Interface the arm with the controller and the sensors



# *Software Management*

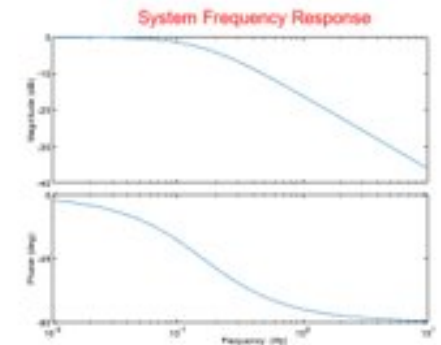
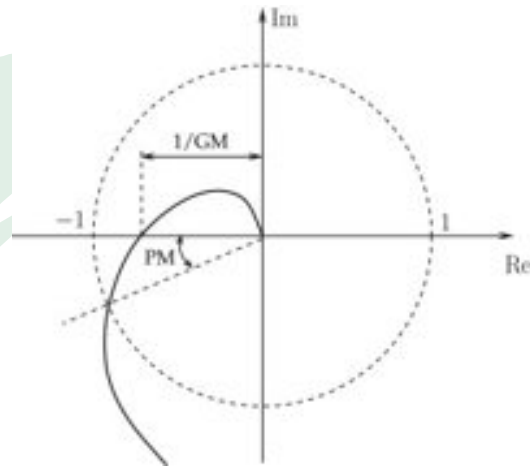
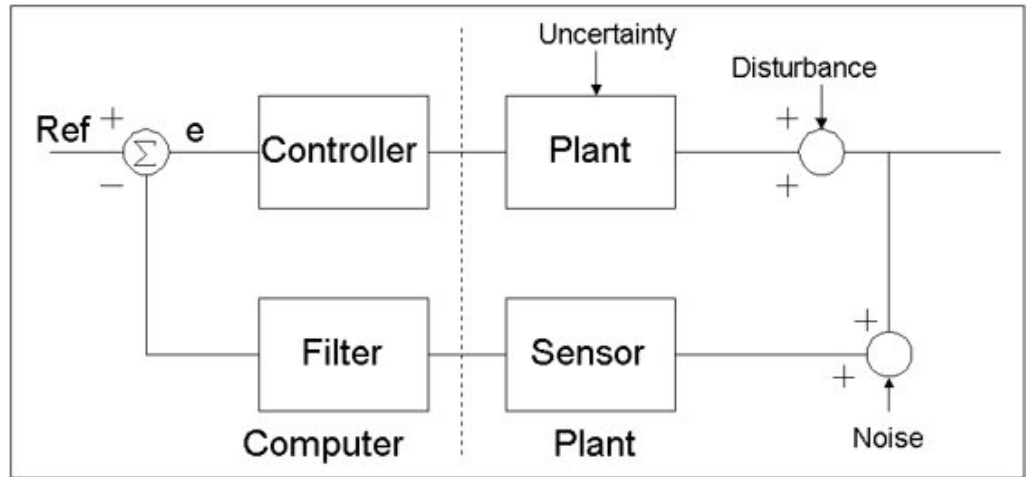
- Docker for Containerizing IOCs and GUI projects
  - Eases maintaining and managing them in different environments.
  - This will make the IOCs portable and able to run on any operating system on any machine - with docker installed - without worrying about dependencies and versions.
  - Moving from development to production is very fast.
- CI/CD on the way!

# Fast Orbit Feedback



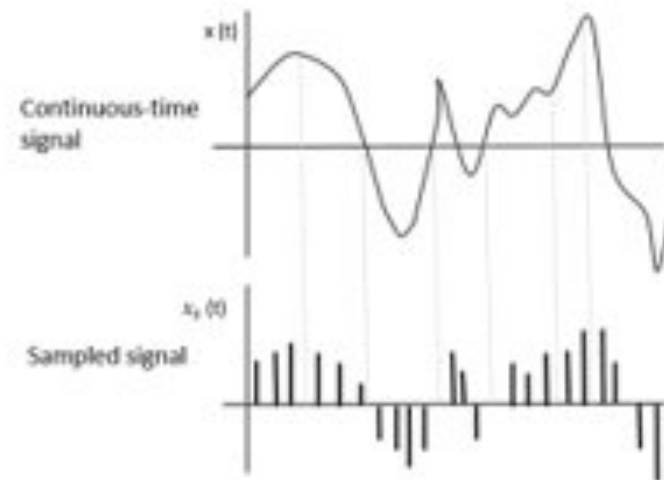
- Correct beam position in the ring
- code in C++ and efficiency is extremely important

# Control System Design



# *Digital Signal Processing*

- Sampling
- Digital filters □





A green brushstroke graphic with a rough, hand-painted edge. The text "Thank You!" is centered within the brushstroke in a white, italicized serif font.

*Thank You!*



# Dr. Khalid Jaber

Associate Professor, IEEE Senior Member

E-Learning & Open Educational Resources Center, Director

Faculty of Science and Information Technology  
Al-Zaytoonah University of Jordan

Ph.D., Computer Science, 2007-2011

Thesis Topic: **Adapting and Enhancing Decision Tree-Based Method to Index Large DNA-Protein Sequence Data Using Hybrid Distributed-Shared Memory Programming Model**

Khalid Jaber, Rosni Abdullah and Nur'Aini Abdul Rashid. A framework for decision tree-based method to index data from large protein sequence databases, 2010 IEEE EMBS Conference on Biomedical Engineering and Sciences (IECBES 2010), Kuala Lumpur, Malaysia, December, 2010.(Scopus).

Khalid Jaber, Rosni Abdullah and Nur'Aini Abdul Rashid. Indexing protein sequence/ structure databases using decision tree: A preliminary study, 4th International Symposium on Information Technology 2010 (ITSim 2010), Vol. 2, Kuala Lumpur Convention Center, Kuala Lumpur, Malaysia, pp. 844-849, June, 2010.(Scopus).

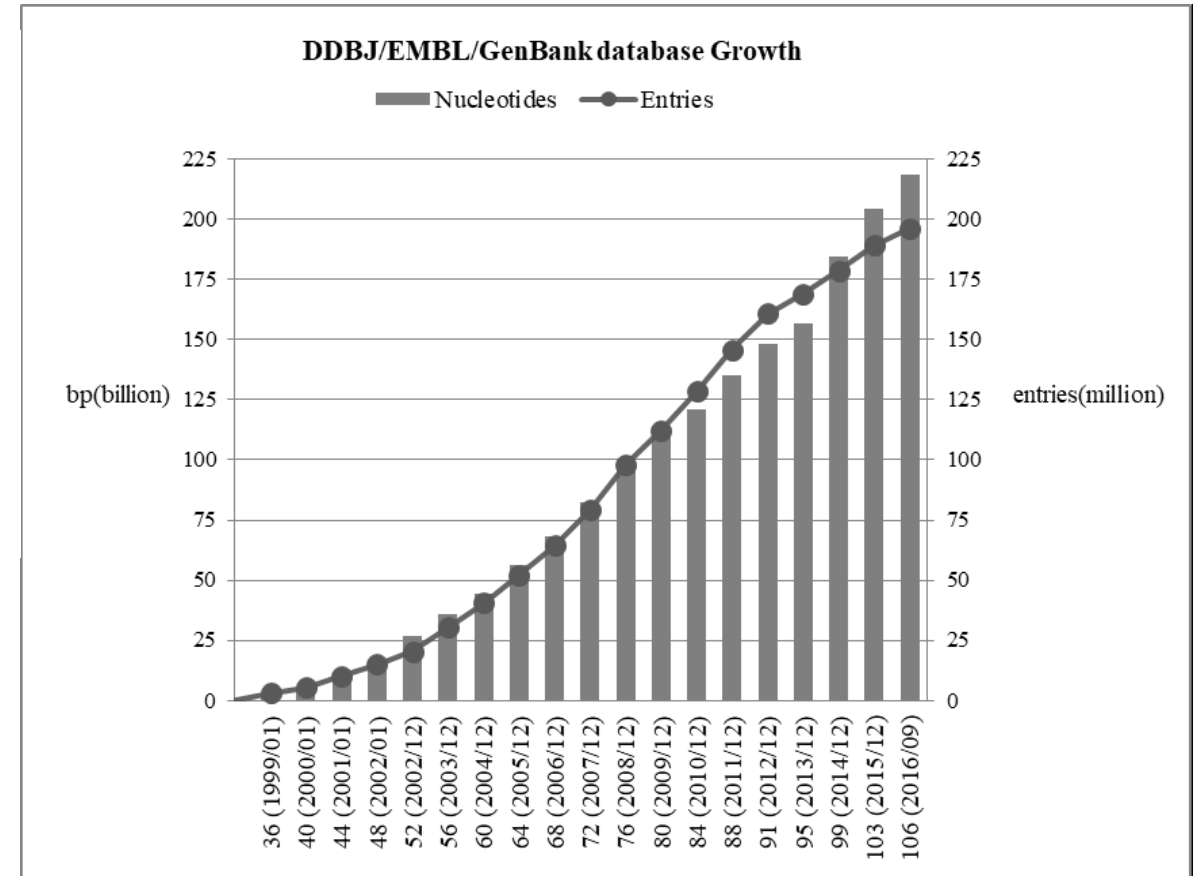
Khalid Jaber, Rosni Abdullah and Nur'Aini Abdul Rashid. A survey of data mining techniques, Symposium of USM Fellowship holders 2009, USM, Penang, Malaysia, pp. 844-849, 2009.

Khalid Mohammad Jaber, Rosni Abdullah and Nur'Aini Abdul Rashid. Adapting Decision Tree-Based Method to Index Large DNA-Protein Sequence Datasets. *The Research Bulletin of Jordan ACM*, Volume II, No. III, September 2011, pp. 57-73.


Khalid Mohammad Jaber, Rosni Abdullah and Nur'Aini Abdul Rashid. Adapting and Enhancing the Searching Algorithm Based on Decision Tree Indexing for Large DNA-Protein Datasets. *The 2011 Conference on Innovations in Computing and Engineering Machinery (CICEM'11)- ACM Chapter Conference*, Vol. 2, pp. 113-122, Grand Hyatt Amman Hotel, Amman, Jordan, 5-6 September, 2011.

Khalid Mohammad Jaber, Rosni Abdullah and Nur'Aini Abdul Rashid. Fast Decision Tree-Based Method to Index Large DNA-Protein Sequence Databases Using Hybrid Distributed-Shared Memory Programming Model. *International Journal of Bioinformatics Research and Applications*, Volume 10, No. III, pp. 321-340, 1 January, 2014.(Scopus).


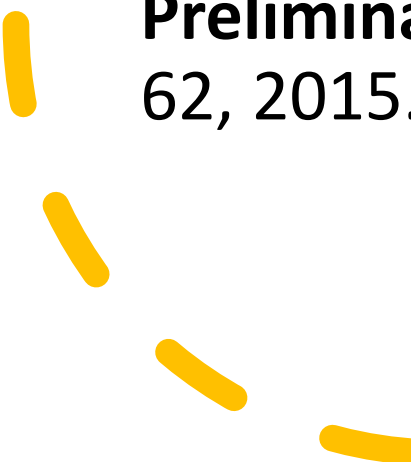
5/29/2023



*The exponential growth of the DDBJ, EMBL and GenBank from 1999 to 2016*



Khalid Mohammad Jaber, Rosni Abdullah and Nur'Aini Abdul Rashid.  
**HDT-HS: A Hybrid Decision Tree/Harmony Search Algorithm for Biological Datasets.** 2012 International Conference on Computer and Information Sciences, Volume 1, pp. 341 - 345, Kuala Lumpur, Malaysia, 12-14 June 2012, (Scopus).

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- Khalid Mohammad Jaber, Sokyna M. Al-Qatawneh, **P-CC-NN: Parallel Cascade Correlation Neural Network Methods for Pattern Recognition applications using Multicore Techniques**, Journal of Theoretical and Applied Information Technology, Vol. 93. No. 1, 2016, (ERA and Scopus).
  - Sokyna M. Al-Qatawneh, Khalid Mohammad Jaber, **Parallel Cascade Correlation Neural Network Methods for 3D Facial Recognition: A Preliminary Study**, Journal of Computer and Communications, 3, 54-62, 2015.
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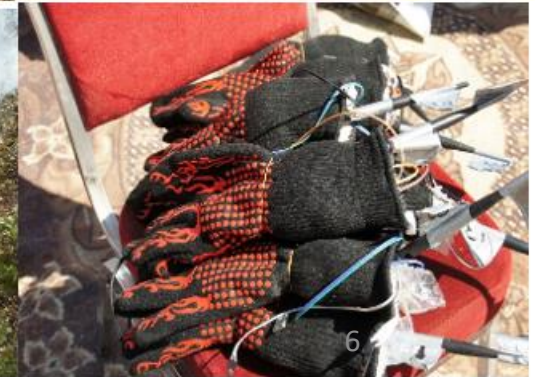
Khalid Mohammad Jaber, Osama Moh'd Alia and Mohammed Mahmod Shuaib, **PHS-SFM: A Parallel Harmony Search Algorithm for the Reproduction of Experimental Data in the Continuous Microscopic Crowd Dynamic Models**, Journal of Experimental and Theoretical Artificial Intelligence, 05 Jan 2018,30:2, Pages 235-255, (IF: 1.384).

Pilgrimage+Evacuation

Adnan Hnaif, Khalid Mohammad Jaber, Mohammad Alia, and Mohammed Daghbosheh, **Parallel scalable approximate matching algorithm for network intrusion detection systems**, International Arab Journal of Information Technology, 2021, 18(1), pp. 77–84, (IF: 0.742).

Sokyna Alqatawneh, Khalid Mohammad Jaber, Mosa Salah, Dalal B. Yehia, Omayma Alqatawneh and Abdulrahman Abulahoum, **Employing of Object Tracking System in Public Surveillance Cameras to Enforce Quarantine and Social Distancing Using Parallel Machine Learning Techniques**, International Journal of Advances in Soft Computing and its Application, 13, 3(2021), 170-180. (Scopus)

# FDPA Internet of Things System for Forest Fire Detection, Prediction and Behaviour Analysis



*Thank You!*  
*very much!*





## Data Collection & Analysis Team



Anas Mohammad\*

Experimental Data Engineer  
*@SESAME -April 2022-*

BSc. in Mechatronics Engineering  
from *HU -2021-*



**Mustafa Alzubi**  
*Data Collection & Analysis  
Team supervisor*

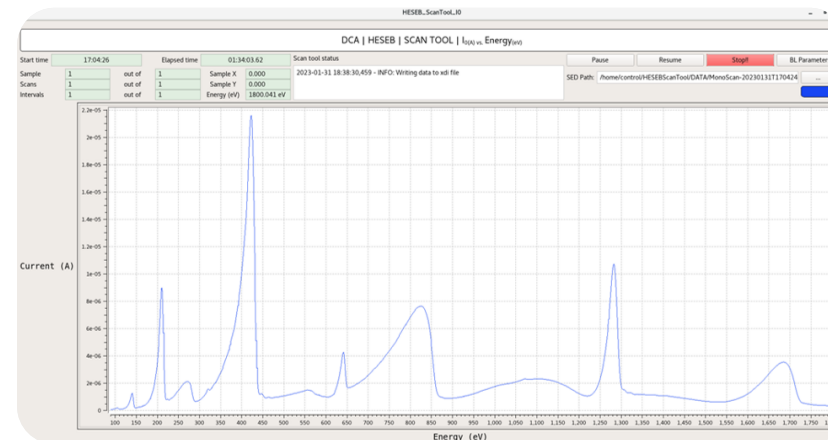


**Anas Mohammad\***

## Data Collection and Analysis team is:

- responsible for providing the essential pre-processing and post-processing tools that are needed to make the data ready for users and scientists to start their own analysis.

UI scanning tool



Live data plotting

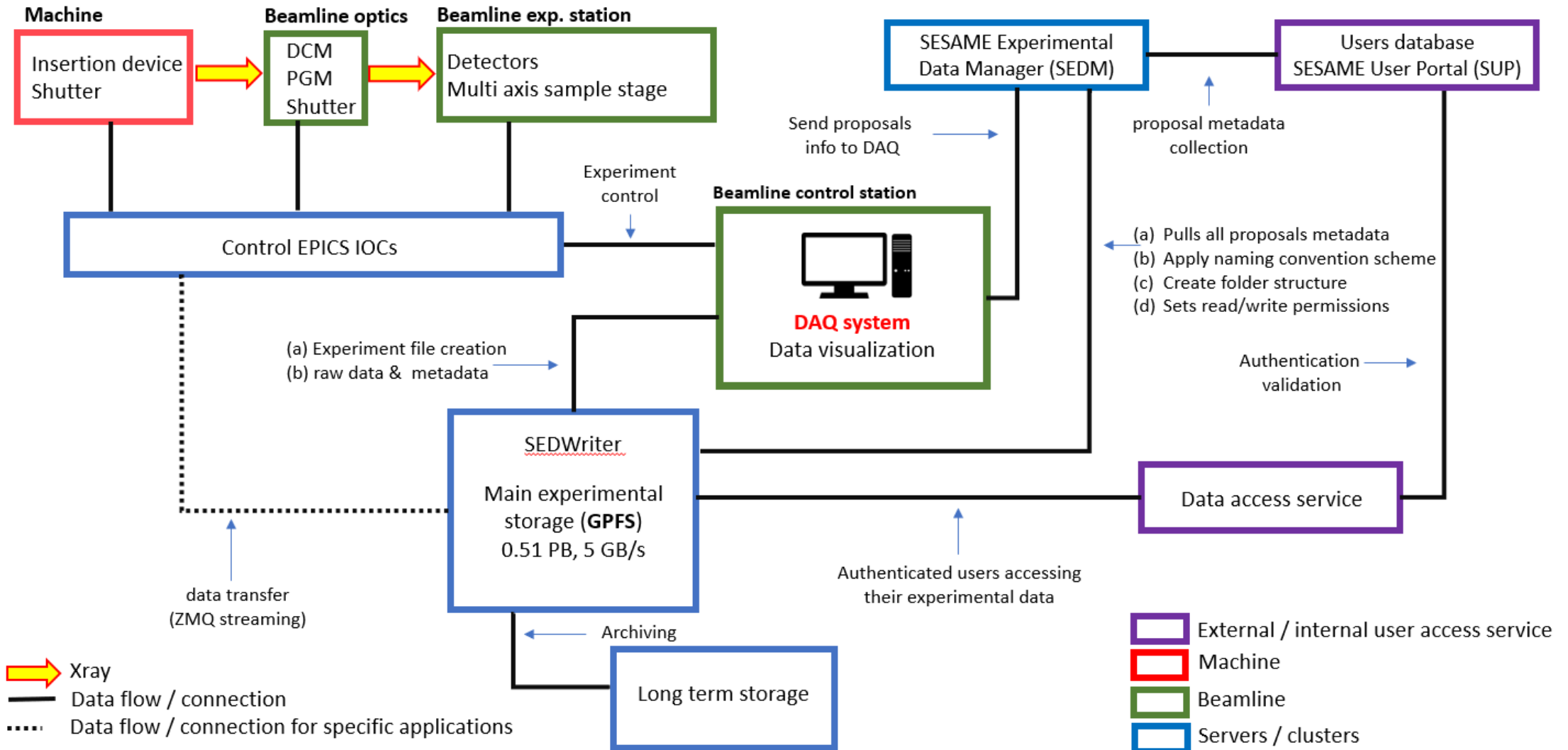
- mainly responsible for ensuring that the experimental data is not randomly generated by acquiring the experimental data and its metadata from the beamlines and other sources, store them together in a stander and well-defined file formats.





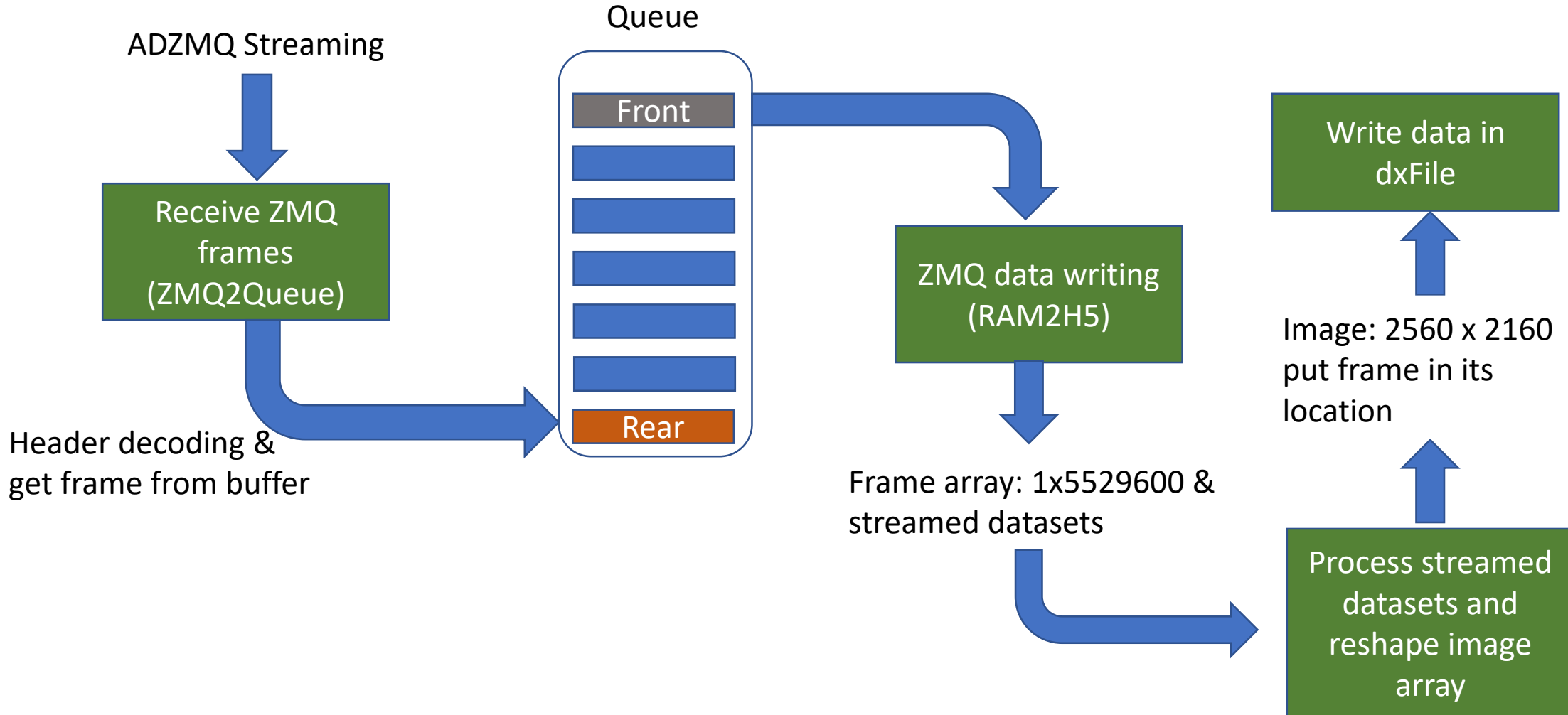
# DAQ General Pipeline

The diagram below shows a general layout of the systems and instruments that are needed for obtaining experimental data at SESAME.



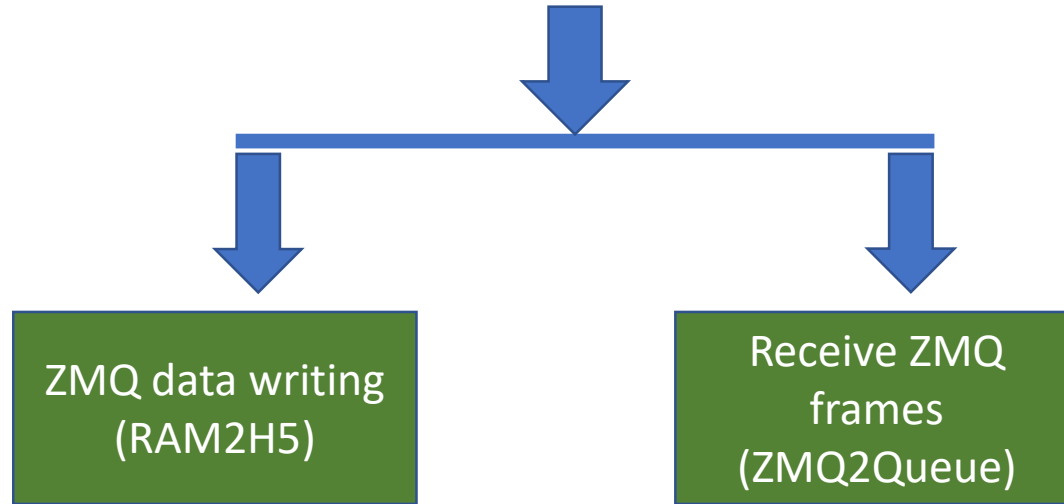


- **BEATSH5Writer:** run the parallel receiving and writing processes





- **BEATSWriter: Components** | run the parallel receiving and writing processes



```
dataQueue = Queue(maxsize=-1) # -1 unlimited queue size
fullH5Path = self.fPath+"/"+self.fName
receivingCounter = Value("i", 0) # Shared integer (i) variables between parallel processes
processingCounter = Value("i", 0) # Shared variable between parrallel processes
ZMQ2Queue = Process(name = "ZMQ2Queue", target=self.ZMQ2Queue, args=((dataQueue),fullH5Path, self.numFrames,
self.frameSizeX, self.frameSizeY, receivingCounter,)) # ZMQ to RAM Process
RAM2H5 = Process(name = "ram2h5", target=self.Queue2HDF5, args=((dataQueue), processingCounter,)) # ZMQ to RAM Process
ZMQ2Queue.daemon = True # to kill all subprocess when when the process is terminated
self.procStartTime = time.time()
ZMQ2Queue.start() #launch the zmq to queue receiving process.
RAM2H5.daemon = True #to kill all subprocess when when the process is terminated
RAM2H5.start() #launch the queue to h5 writing process.
```



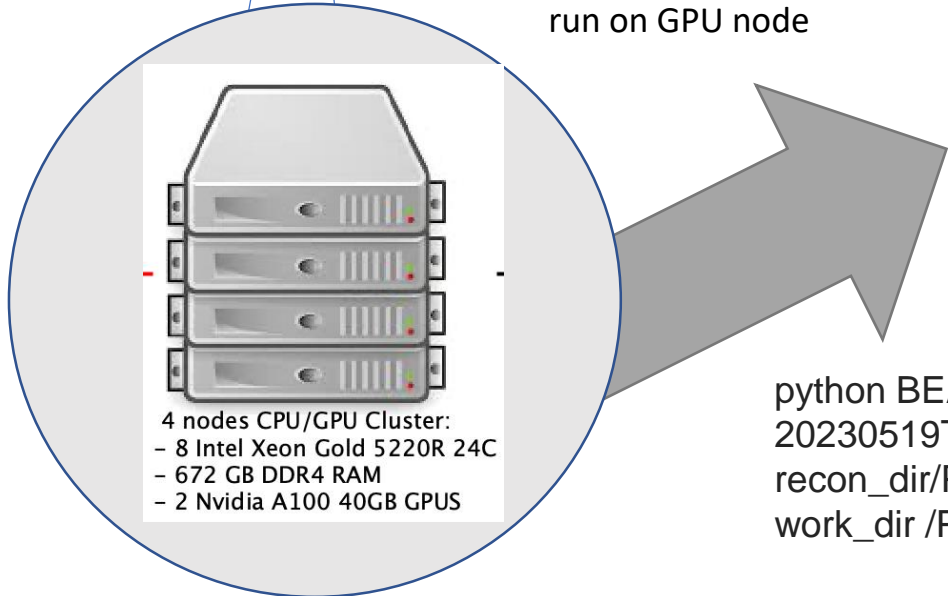
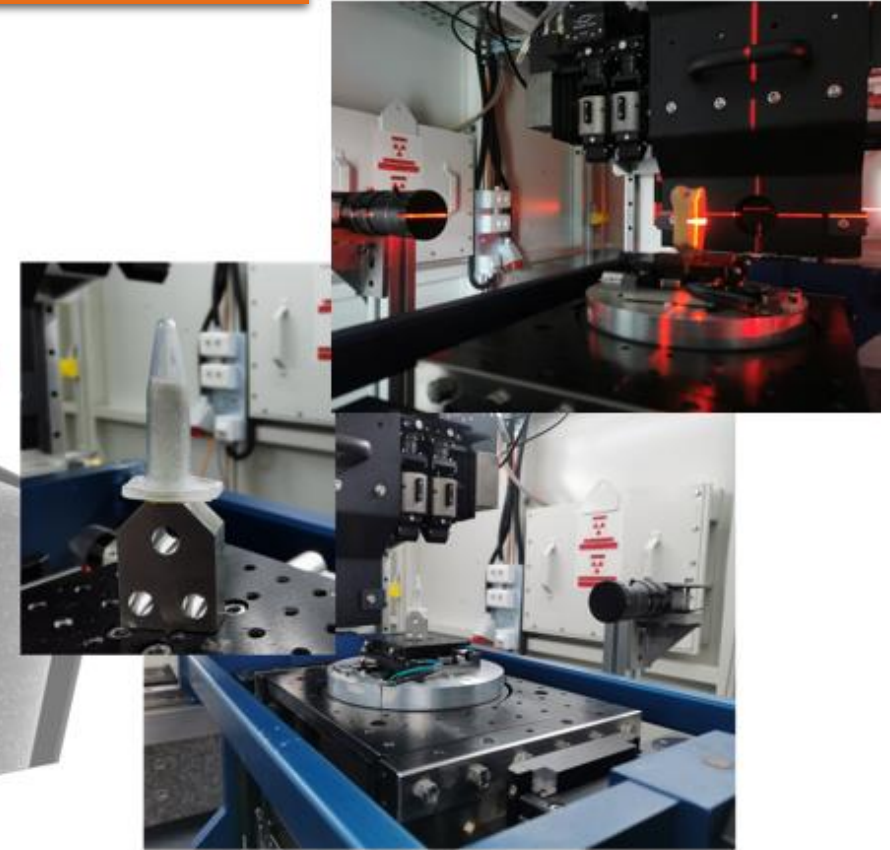
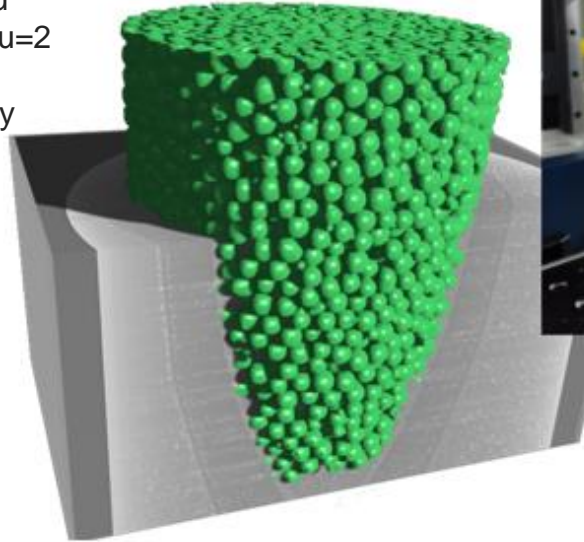
## HPC Cluster

## First 3D tomography images from BEATS



```
#!/bin/bash
#SBATCH --job-name=BEATS_rec_%j
#SBATCH --output=BEATS_rec_%j.out
#SBATCH --error=BEATS_rec_%j.err
#SBATCH --ntasks=48
#SBATCH --cpus-per-task=2
#SBATCH --time=00:30:00
#SBATCH --partition=cpu
#SBATCH --mem-per-cpu=2
# Modules section:
ml load anaconda/tomopy
```

Reconstruction Job  
run on GPU node



4 nodes CPU/GPU Cluster:  
 - 8 Intel Xeon Gold 5220R 24C  
 - 672 GB DDR4 RAM  
 - 2 Nvidia A100 40GB GPUS

```
python BEATS_recon.py /PETRA/SED/BEATS/IH/glass_speres_coral-20230519T190251/red_sea_coral-20230519T190251.h5 --recon_dir/PETRA/SED/BEATS/IH/tmp/recon --work_dir /PETRA/SED/BEATS/IH/tmp --cor_methodtomopy --ncore 92
```



SESAME



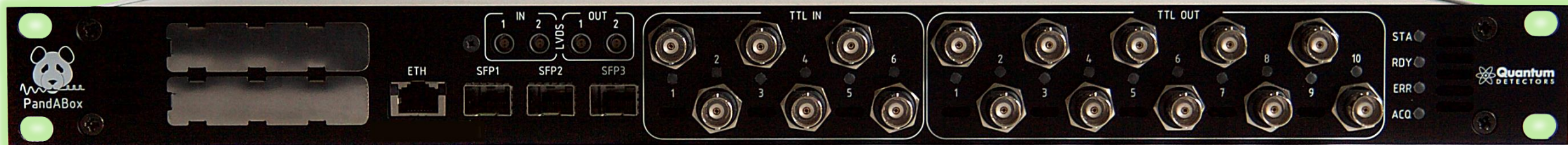
## SESAME-MAXIV Fellowship

31 Oct, 2022 – 30 Dec 2022

**Data Acquisition System -More focus on hardware  
and continuous scan technique**



PandABox is a fully integrated position, acquisition and control system with GTX-CLK0 up to 125MHz.







# OnFly Scan | Fast Data Acquisition | MS Beamline

SESAME



Encoder Readouts

PandABox



TTL triggers

Captured data

Streamed Big data

Parallel programming C++  
Reshaping, Extract ROI from each frame,  
apply some basic operations

Processed data



Frequency 500Hz

Thanks!

Any Question!

